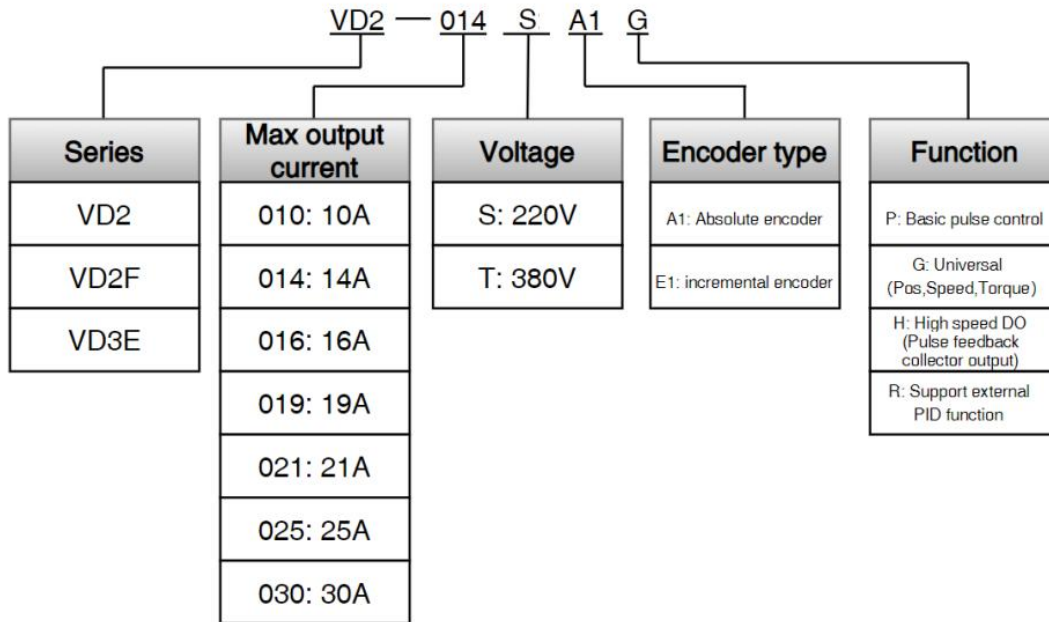
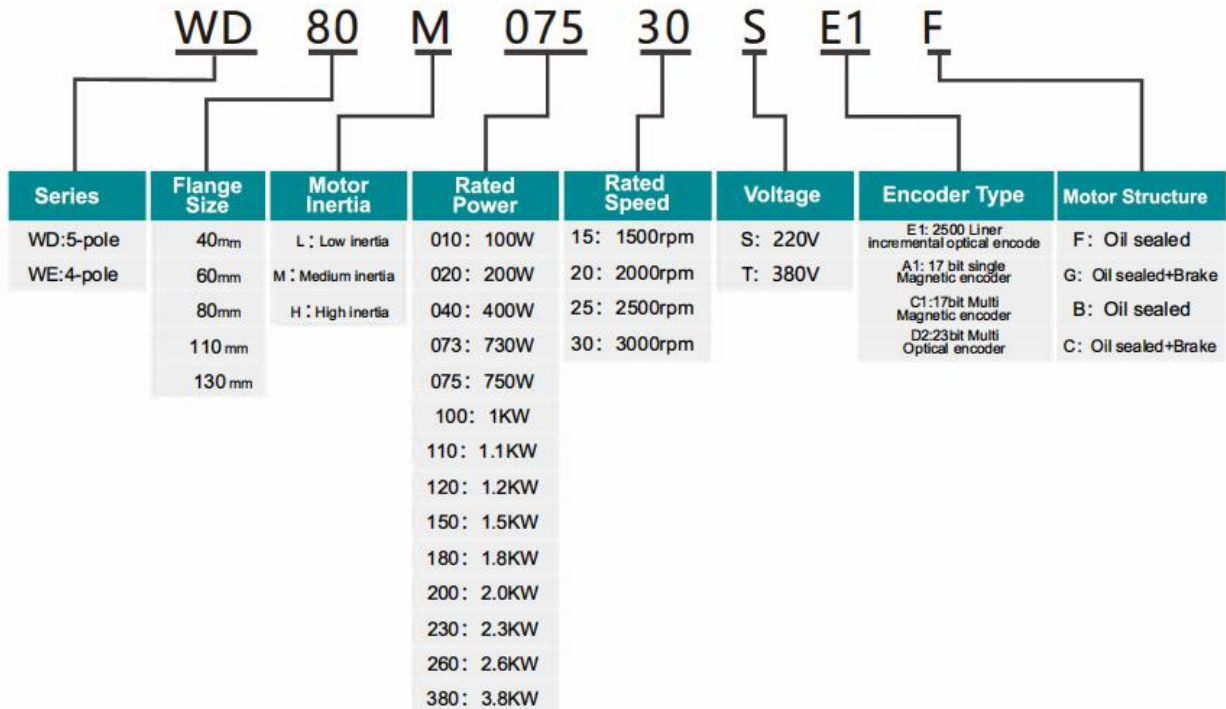


Drive Naming Rules



Motor Naming Rules



VD3E 17 bit Absolute Single-turn Magnetic Encoder

Flange Size	Motor Model	Drive Model	Rated Torque (N.m)	Rated Speed (rpm)	Voltage
60	WE60M-04030S-A1F	VD3E-010SA1G	1.27	3000	220V
80	WE80M-07530S-A1F	VD3E-014SA1G	2.39	3000	220V
80	WE80M-07320S-A1F	VD3E-014SA1G	3.5	2000	220V
80	WE80M-11030S-A1F	VD3E-016SA1G	3.5	3000	220V
80	WE80M-10025S-A1F	VD3E-016SA1G	4	2500	220V
80	WE80M-12030S-A1F	VD3E-016SA1G	4	3000	220V
110	WE110M-12030S-A1F	VD3E-016SA1G	4	3000	220V
110	WE110M-15030S-A1F	VD3E-019SA1G	5	3000	220V
110	WE110M-18030S-A1F	VD3E-019SA1G	6	3000	220V
130	WE130M-10025S-A1F	VD3E-016SA1G	4	2500	220V
130	WE130M-13025S-A1F	VD3E-016SA1G	5	2500	220V
130	WE130M-15025S-A1F	VD3E-019SA1G	6	2500	220V
130	WE130M-20025S-A1F	VD3E-021SA1G	7.7	2500	220V
130	WE130M-15015S-A1F	VD3E-019SA1G	10	1500	220V
130	WE130M-23015S-A1F	VD3E-021SA1G	15	1500	220V
130	WE130M-38025S-A1F	VD3E-030SA1G	15	2500	220V

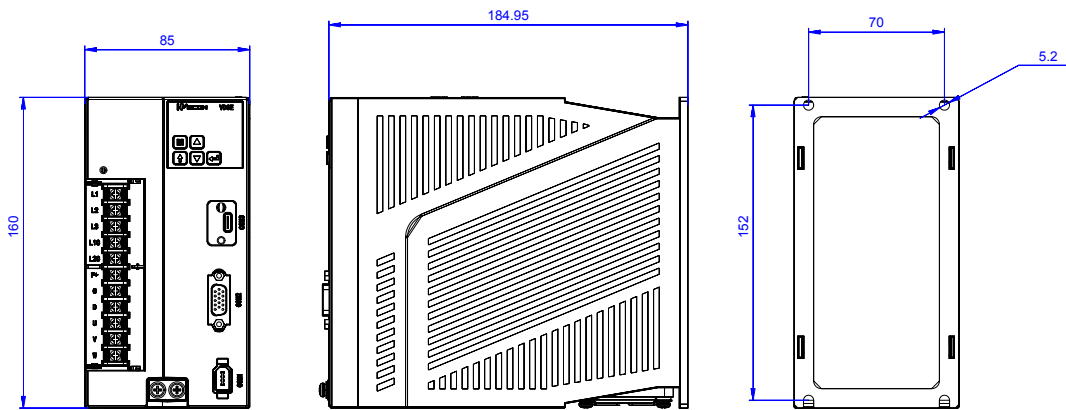


VD3E 17 bit Absolute Multi-turn Magnetic Encoder

Flange Size	Motor Model	Drive Model	Rated Torque (N.m)	Rated Speed (rpm)	Voltage
80	WE80M-11030S-C1F	VD3E-016SA1G	3.5	3000	220V
80	WE80M-12030S-C1F	VD3E-016SA1G	4	3000	220V
110	WE110M-12030S-C1F	VD3E-016SA1G	4	3000	220V
110	WE110M-15030S-C1F	VD3E-019SA1G	5	3000	220V
110	WE110M-18030S-C1F	VD3E-019SA1G	6	3000	220V
130	WE130M-10025S-C1F	VD3E-016SA1G	4	2500	220V
130	WE130M-13025S-C1F	VD3E-016SA1G	5	2500	220V
130	WE130M-15025S-C1F	VD3E-019SA1G	6	2500	220V
130	WE130M-20025S-C1F	VD3E-021SA1G	7.7	2500	220V
130	WE130M-15015S-C1F	VD3E-016SA1G	10	1500	220V
130	WE130M-26025S-C1F	VD3E-021SA1G	10	2500	220V
130	WE130M-23015S-C1F	VD3E-019SA1G	15	1500	220V
130	WE130M-38025S-C1F	VD3E-021SA1G	15	2500	220V
130	WE130M-38025S-C1F	VD3E-030SA1G	15	2500	220V

VD3E 23 bit Absolute Multi-turn Optical Encoder

Flange Size	Motor Model	Drive Model	Rated Torque (N.m)	Rated Speed (rpm)	Voltage
80	WE80M-11030S-D2F	VD3E-016SA1G	3.5	3000	220V
80	WE80M-12030S-D2F	VD3E-016SA1G	4	3000	220V
110	WE110M-12030S-D2F	VD3E-016SA1G	4	3000	220V
110	WE110M-15030S-D2F	VD3E-019SA1G	5	3000	220V
110	WE110M-18030S-D2F	VD3E-019SA1G	6	3000	220V
130	WE130M-10025S-D2F	VD3E-016SA1G	4	2500	220V
130	WE130M-13025S-D2F	VD3E-016SA1G	5	2500	220V
130	WE130M-15025S-D2F	VD3E-019SA1G	6	2500	220V
130	WE130M-20025S-D2F	VD3E-021SA1G	7.7	2500	220V
130	WE130M-15015S-D2F	VD3E-016SA1G	10	1500	220V
130	WE130M-26025S-D2F	VD3E-021SA1G	10	2500	220V
130	WE130M-23015S-D2F	VD3E-019SA1G	15	1500	220V
130	WE130M-38025S-D2F	VD3E-021SA1G	15	2500	220V
130	WE130M-26025S-D2F	VD3E-021SA1G	10	2500	220V
130	WE130M-38025S-D2F	VD3E-021SA1G	15	2500	220V
130	WE130M-38025S-D2F	VD3E-030SA1G	15	2500	220V



SPECIFICATION

Basic Specifications	Power Supply	220V / 380V
	Control Method	IGBT PWM control sine wave current drive
	Encoder Feedback	17bit/23bit absolute encoder
	Control Signal Input	6 DI inputs, select the input function according to the function code configuration
	Control Signal Output	3 DO outputs, select the output function according to the function code configuration
	Communication	USB interface. Function code parameter setting, status monitoring, waveform viewing, parameter self-tuning, etc. can be performed through upper computer
	Braking Resistor	Built-in braking resistor, support external braking resistor
General Function	Automatic Parameter Tuning	Automatic load inertia identification, automatic rigidity level and parameter self-tuning can be carried out through the cooperation of the upper computer
	Waveform View	The waveform of data such as real-time speed/torque/position deviation can be observed through the host computer
	Waveform Storage	The waveform acquisition frequency is 1KHz, and the original waveform data can be saved up to 10s
	Parameter import and	Support batch parameter import and export; support SDO download
	Vbration Suppression	Mechanical vibration can be suppressed by setting vibration suppression parameters
	Protective Function	Overvoltage, undervoltage, overcurrent, overspeed, overload, overheating, encoder failure, excessive position deviation, torque limit, speed limit, etc.
	Brake	Support output control
	Universal Control DI input	Servo enable (SON), fault and warning clear (A-CLR), forward drive prohibition (POT), reverse drive prohibition (NOT), emergency stop (E-STOP)
EtherCAT	General Control DO Output	servo ready(RDY), fault signal (ALM), warning signal (WARN), rotation detection (TGON), zero speed signal (ZSP), torque limit (T-LIMIT), speed limit (V- LIMIT), servo open state output (SRV-ST), servo brake output (BRK-OFF), communication VDO
	Communication	EtherCAT protocol
	Support Service	CoE (PDO, SDO)
	Synchronously	DC-distributed clock
	physical layer	100BASE-TX
	Baud rate	100 Mbit/s (100Base-TX)
	Duplex Mode	full duplex
	Topology	circular, linear
	Transmission	Shielded Cat 5e or better network cable.
	Transmission distance	The distance between two nodes is less than 100M (the environment is good and the cable is good).
	Number of Slave Stations	The protocol supports up to 65535, and the actual use does not exceed 100.
	Frame Length	44 bytes~1498 bytes
	Process Data	A single Ethernet frame is up to 1486 bytes.
	Sync Jitter	<1us
	Distributed Clock	64 bit
	EEPROM Capacity	8kbit initialization data is written by the EtherCAT master station
	Control Mode	CSP、HM
Sync Cycle	125μs	